



SCUBA-2 system interfaces













SCUBA-2 Website: http://www.roe.ac.uk/atc/projects/scuba_two





Outline

- Current status of SCUBA-2 detector development
- Key system technologies for focal plane integration

Posters and talks:-

Y11 (Ullom), RO4 (Hilton), Y25,26 (Audley), Y27 (Ullom), E05 (Doriese), E01 (Irwin)

Cover in detail array construction and manufacture, pixel test results and multiplexer design as well as ideas for excess noise reduction.

Arrays



Tested single pixels with Tc's and power handling appropriate for handling the back ground power loading at both 450 and 850 μ m's.

- •NEP's meets specification of low * 10-17 W/sqrt Hz. Some excess noise at 450 μm
- •Time constants 1 msec or less (to 70 μ sec).
- •Tc variation <7mK in 140mK across a test wafer
- •Responsivity measured with both heater and IV power

Multiplexer

1 * 32 test chip measured for speed and 1/f SQUID noise reduction using dark SQUID. SCUBA-2 unit cell developed and tested

Three major changes to design since last LTD:-







Processes Bump bonding demonstrated

Thermal conductance of bumps measured and no. of bumps per pixel chosen (60).

Deep RIE etching after bump bonding demostrated

Doping to achieve 400 ohm per sq for absorber measured for both n and p type wafers

Wafer bonding demonstrated

Final masks now under fabrication expect in-hand example of prototype by end of this year detailed tests by end of March 2004.

System interfaces for arrays



• Optical

QE; stray light; background; filters; alignment of arrays;

• Thermal

focal plane power dissipation; attachment to refrigerator, thermal cross talk, achieving operating temperature

Mechanical

optical alignment, stiffness v's heat leak; hold arrays flat; sub-array buttable solutions; easy installation

• Electrical

signal, bias and multiplexer clock connections; heat leak; connection density

• Cryogenics

base temperature; cooling power; long cooling path; temperature stability



System interfaces for arrays

As focal planes become larger coping with these system issues becomes much more difficult and expensive

anted @ SCUBA-2 - integration of the focal planes **Astronomical + background** photons+ bias power • 1µW **Electrical connections -**1200 per focal plane Focal plane (4 sub-arrays) **Connection to dilution** • power dissipation 2-3.5 μW • < 2 μ W heat leak refrigerator • very low impedance • 5-6.5 µwatt heat flow • 35 mK • Boundary resistance

- Differential contraction
- Hold arrays flat

Mechanical support

- Resonant frequency ~ 100 Hz
- Accurately locates and supports up to 7 kg
- $\bullet < 2~\mu W$ heat leak (to dilution refrigerator only)







- Kevlar/carbon cloth wheels
- ~ 140 mm dia.
- 0.1 mm thickness
- $<2\;\mu W$ heat leak from 1K
- high stiffness and easy to manufacture

Electrical interface - kapton flex

- •Niobium tracks
- •50 micron Kapton, 55 mm length, 44 mm wide
- •12 flex per focal plane
- •Heat leak ~ 1.6 μ W (1K to 40 mK)
- •spare tracks (10%)
- •z-axis adhesive
- •track pitch of 380 μm
- •thermally cycles
- •contact resistance being measured at 4K





Connection to dilution refrigerator

- •Be/Cu 'hair brush'
- Tines ~ 0.5 by 0.5 mm cross section, 21 mm long on 1.135 mm pitch
- •Head of pins is ~ 1mm by 1mm
- •Arrays epoxied to hair brush
- •Good thermal transport (~7 mK drop across interface)
- •Thermally cycles
- •Low thermal stresses
- •Holds arrays flat
- •Large dilution refrigerator

400+ μ W at 100 mK to give 20 μ W @ 25 mK

